



UNIVERSITAT POLITÈCNICA  
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BARCELONATECH

**Computational Structural Mechanics and Dynamics**

# Assignment 10

Assignment: Dynamics

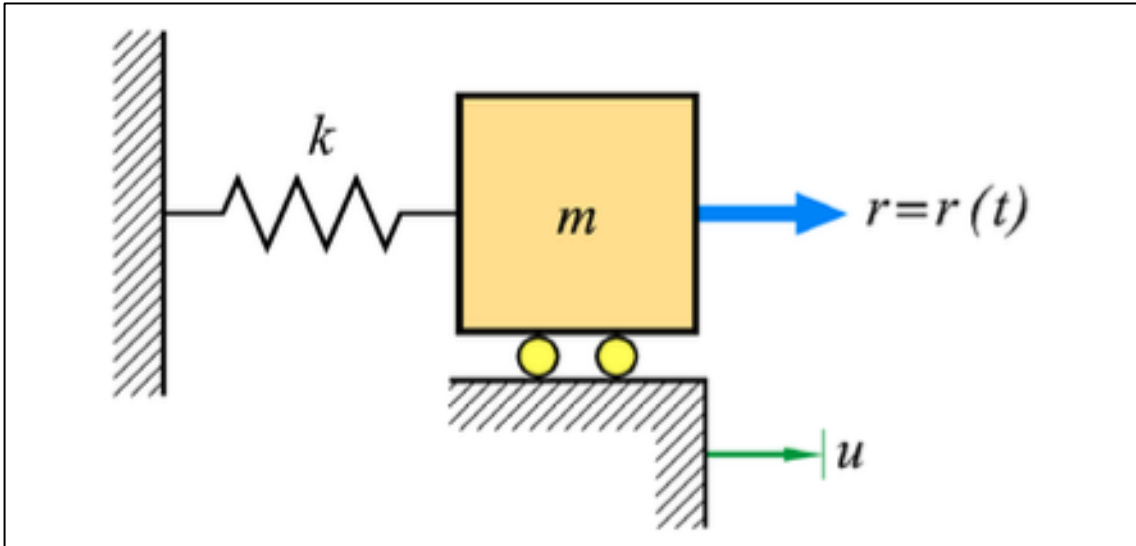
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# SUMMARY

QUESTION 1	2
QUESTION 2	3
QUESTION 3	3
QUESTION 4	4
QUESTION 5	4

## Question 1

1. In the dynamic system of slide 6, let  $r(t)$  be a constant force  $F$ . What is the effect of  $F$  on the time-dependent displacement  $u(t)$  and the natural frequency of vibration of the system?



The differential equation which governs this harmonic system is

$$ku + mu \ddot{=} F$$

The solution of this Non-homogeneous ODE can be represented as the superposition of the homogeneous solution and the particular solution.

$$u(t) = u_h + u_p$$

For this particular ODE the homogeneous solution takes the form

$$u_h = A \sin(\omega t) + B \cos(\omega t)$$

And taking into account that  $F$  has no time dependence, the particular solution can be obtained through a constant

$$u_p = u_0 ; \dot{u}_p = 0 ; \ddot{u}_p = 0$$

Therefore,

$$ku_0 = F \rightarrow u_p = \frac{F}{k}$$

Superposing this result with the one of the homogeneous solution

$$u(t) = A \sin(\omega t) + B \cos(\omega t) + \frac{F}{k}$$

Applying the initial conditions  $u(0) = 0$  and  $\dot{u}(0) = 0$

$$A = 0, B = -\frac{F}{k}$$

Finally the expression of  $u(t)$  results as

$$u(t) = \frac{F}{k}(1 - \cos(\omega t))$$

Being  $\omega = \sqrt{\frac{K}{m}}$  the natural frequency of the system

As can be seen, the constant force  $F$  does not affect the natural frequency of the system. Meanwhile the amplitude of the system is clearly dependent of the force magnitude.

## Question 2

2. A weight whose mass is  $m$  is placed at the middle of a uniform axial bar of length  $L$  that is clamped at both ends. The mass of the bar may be neglected. Estimate the natural frequency of vibration in terms of  $m$ ,  $L$ ,  $E$  and  $A$ . Suggestion: First determine the effective  $k$ .

The effective stiffness of a beam can be analytically derived from the equation of the beam deflection when a punctual force is applied.

$$k = \frac{F}{\delta} = \frac{mg}{\delta}$$

In order to determine this parameter the deflection of the beam at the force application point is needed.

$$\delta\left(\frac{L}{2}\right) = \frac{FL^3}{192EI} = \frac{mgL^3}{192EI}$$

Substituting this expression in the one of the effective stiffness the estimation of the natural frequency results as

$$\omega = \sqrt{\frac{192EI}{mL^3}}$$

Being  $I$  the inertia of the cross section which depends on the area  $A$ .

## Question 3

3. Use the expression on slide 18 to derive the mass matrix of slide 17.

The general form of the consistent element mass matrix is

$$M = \int_{l^e} \rho N^T N dV$$

The shape functions are

$$N_1 = 1 - \xi ; N_2 = \xi$$

Therefore, integrating respect to the reference coordinates, the integral results as

$$M = \rho AL \int_0^1 \begin{bmatrix} (1-\xi)^2 & (1-\xi)\xi \\ (1-\xi)\xi & \xi^2 \end{bmatrix} d\xi$$

And finally, the result of this integral is the same as the indicated in the slide 19

$$M = \frac{\rho AL}{6} \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$$

## Question 4

4. Obtain also the mass matrix of a two-node, linear displacement element with a variable cross-sectional area that varies from  $A_1$  to  $A_2$ .

The formulation to compute the cross sectional area is the following

$$A = N_1 A_1 + N_2 A_2$$

Being the shape functions analogous to the previous linear ones employed in the question 3.

The expression of the mass matrix is again the general form

$$M = \int_{l^e} \rho N^T N dV$$

Now  $dV$  depends on  $x$  and is expressed as  $dV = A(x)dx$ . If this differential is expressed in the reference coordinates the result of the integral is

$$M = \rho L \int_0^1 \begin{bmatrix} N_1 \\ N_2 \end{bmatrix} [N_1 \quad N_2] [N_1 A_1 + N_2 A_2] d\xi$$

Therefore,

$$M = \rho L \left( A_1 \int_0^1 \begin{bmatrix} (1-\xi)^3 & (1-\xi)^2 \xi \\ (1-\xi)^2 \xi & (1-\xi)\xi^2 \end{bmatrix} d\xi + A_2 \int_0^1 \begin{bmatrix} (1-\xi)^2 \xi & (1-\xi)\xi^2 \\ (1-\xi)\xi^2 & \xi^3 \end{bmatrix} d\xi \right)$$

The resultant mass matrix is

$$M = \frac{\rho L}{12} \left( A_1 \begin{bmatrix} 3 & 1 \\ 1 & 1 \end{bmatrix} + A_2 \begin{bmatrix} 1 & 1 \\ 1 & 3 \end{bmatrix} \right) = \frac{\rho L}{12} \begin{bmatrix} 3A_1 + A_2 & A_1 + A_2 \\ A_1 + A_2 & A_1 + 3A_2 \end{bmatrix}$$

If  $A_1 = A_2$  the expression of the constant section mass matrix is recovered

## Question 5

5. A uniform two-node bar element is allowed to move in a 3D space. The nodes have only translational d.o.f. What is the diagonal mass matrix of the element?

The diagonal mass matrix of this particular element in 3D is the following lumped mass matrix, which is very useful in terms of saving computational costs.

$$M = \frac{\rho AL}{2} I_6 = \frac{\rho AL}{2} \begin{bmatrix} 1 & & & & & \\ & 1 & & & & \\ & & 1 & & & \\ & & & 1 & & \\ & & & & 1 & \\ & & & & & 1 \end{bmatrix}$$