

1 Prove the identity of the conservative and non-conservative forms of the momentum conservation equation

$$\rho \frac{\partial \mathbf{v}}{\partial t} + \rho(\mathbf{v} \cdot \nabla)\mathbf{v} - \nabla \cdot \sigma = \rho \mathbf{b} \leftrightarrow \frac{\partial(\rho \mathbf{v})}{\partial t} + \nabla \cdot (\rho \mathbf{v} \otimes \mathbf{v} - \sigma) = \rho \mathbf{b} \quad (1)$$

Starting from the conservative form of the linear momentum equation, it is possible to derive the following:

$$\frac{\partial \rho \mathbf{v}}{\partial t} + \nabla \cdot (\rho \mathbf{v} \otimes \mathbf{v} - \sigma) = \rho \mathbf{b} \quad (2)$$

$$\rho \frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v} \otimes \mathbf{v}) - \nabla \cdot \sigma = \rho \mathbf{b} \quad (3)$$

The third term of the equation (3) can be analyzed as it follows:

$$\nabla \cdot (\rho \mathbf{v} \otimes \mathbf{v}) = \begin{bmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \end{bmatrix} \begin{bmatrix} \rho u u & \rho u v & \rho u z \\ \rho v u & \rho v v & \rho v z \\ \rho w u & \rho w v & \rho w z \end{bmatrix} \quad (4)$$

We can find the x-component as:

$$\begin{aligned} & \frac{\partial(\rho u u)}{\partial x} + \frac{\partial(\rho v u)}{\partial y} + \frac{\partial(\rho w u)}{\partial z} \\ & \rho \left(\frac{\partial(uu)}{\partial x} + \frac{\partial(vu)}{\partial y} + \frac{\partial(wu)}{\partial z} \right) + u \left(u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} \right) \\ & \rho \left(u \frac{\partial u}{\partial x} + u \frac{\partial u}{\partial x} + u \frac{\partial v}{\partial y} + v \frac{\partial u}{\partial y} + u \frac{\partial w}{\partial z} + w \frac{\partial u}{\partial z} \right) + u [u \ v \ w] \cdot \begin{bmatrix} \frac{\partial \rho}{\partial x} & \frac{\partial \rho}{\partial y} & \frac{\partial \rho}{\partial z} \end{bmatrix} \\ & \rho \left(u \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right) + u(\mathbf{v} \cdot \nabla \rho) \\ & \rho \left(u \nabla \cdot \mathbf{v} + [u \ v \ w] \cdot \begin{bmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} & \frac{\partial u}{\partial z} \end{bmatrix} \right) + u(\mathbf{v} \cdot \nabla \rho) \end{aligned}$$

$$\rho \left(u(\nabla \cdot \mathbf{v}) + \mathbf{v} \cdot \nabla u \right) + u(\mathbf{v} \cdot \nabla \rho)$$

And analogous the y-component and z-component. The following identity is satisfied:

$$\nabla \cdot (\rho \mathbf{v} \otimes \mathbf{v}) = \rho \left(\mathbf{v}(\nabla \cdot \mathbf{v}) + \mathbf{v} \cdot \nabla \mathbf{v} \right) + \mathbf{v}(\mathbf{v} \cdot \nabla \rho) \quad (5)$$

Using the chain rule:

$$\rho \left(\mathbf{v}(\nabla \cdot \mathbf{v}) + \mathbf{v} \cdot \nabla \mathbf{v} \right) + \mathbf{v} \left(\nabla \cdot (\rho \mathbf{v}) - \rho(\nabla \cdot \mathbf{v}) \right)$$

$$\rho \mathbf{v}(\nabla \cdot \mathbf{v}) + \rho \mathbf{v} \cdot \nabla \mathbf{v} + \mathbf{v} \nabla \cdot (\rho \mathbf{v}) - \rho \mathbf{v}(\nabla \cdot \mathbf{v})$$

$$\rho \mathbf{v} \cdot \nabla \mathbf{v} + \mathbf{v} \nabla \cdot (\rho \mathbf{v})$$

Substituting into the original equation:

$$\rho \frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \frac{\partial \rho}{\partial t} + \rho \mathbf{v} \cdot \nabla \mathbf{v} + \mathbf{v} \nabla \cdot (\rho \mathbf{v}) - \nabla \cdot \sigma = \rho \mathbf{b}$$

$$\rho \frac{\partial \mathbf{v}}{\partial t} + \rho(\mathbf{v} \cdot \nabla) \mathbf{v} + \mathbf{v} \left(\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) \right) - \nabla \cdot \sigma = \rho \mathbf{b}$$

$$\boxed{\rho \frac{\partial \mathbf{v}}{\partial t} + \rho(\mathbf{v} \cdot \nabla) \mathbf{v} - \nabla \cdot \sigma = \rho \mathbf{b}}$$