



Titulació Prakhar Rastogi

Assignatura FEF Risit

Cognoms _____ Nom _____

DNI _____

Pàgina _____ de _____

Master in Computational Mechanics

Ex-1

$$-\gamma u_{xx} + \beta u_x = 0, \quad x \in (0, 1)$$

$$u = 0, \quad x = 0$$

$$u = 1, \quad x = 1$$

} Dirichlet B.C

~~→~~

(a) $S := \{u \in H^1(\Omega) \mid u = 0 \text{ on } x = 0 \text{ \& } u = 1 \text{ on } x = 1\}$

$V := \{w \in H^1(\Omega) \mid w = 0 \text{ on } \Gamma_D\}$

$$-\nabla \cdot \gamma \nabla u + \beta \cdot \nabla u = 0$$

$$\int_{\Omega} w \nabla \cdot (\gamma \nabla u) d\Omega + \int_{\Omega} w (\beta \cdot \nabla u) d\Omega = 0$$

using $w = 0$ on Γ_D and integrating by parts

$$\int_{\Omega} \nabla w \cdot (\gamma \nabla u) d\Omega + \int_{\Omega} w (\beta \cdot \nabla u) d\Omega = 0$$

$$\Rightarrow \boxed{a(w, u) + c(\beta, w, u) = 0}$$

(b) $a^h(w^h, u^h) + c(\beta, w^h, u^h) = 0 \quad \forall w^h \in V^h$

$$u^h(x) = \sum_{B \in \mathcal{T}_D} N_B(x) u_B + \sum_{B \in \mathcal{T}_D} N_B(x) u_D(x_B)$$

$$w^h \in V^h$$

Discrete form

$$\sum_{B \in \Omega_D} [a(N_A, N_B) + c(\beta; N_A, N_B)] u_B = - \sum_{B \in \Omega_D} [a(N_A, N_B) + c(\beta; N_A, N_B)] u_D(x_B)$$

Now input the B.C

$$\sum_{B \in \Omega_D} [a(N_A, N_B) + c(\beta; N_A, N_B)] u_B = - [a(N_A, N_B) + c(\beta; N_A, N_B)] u_D(x_B)$$

(u = 1 at x = 1)
(u = 0 at x = 0)

Convection Matrix

$$(C + K) u = f$$

$$C = A^e C^e \quad C_{ab}^e = \int \Omega_a (\beta \cdot \nabla N_b) d\Omega$$

$$K = A^e K^e \quad K_{ab}^e = \int \nabla N_a \cdot \nu \nabla N_b d\Omega$$

Diffusion Matrix

$$f_a^e = \sum_{b=1}^{n_{en}} [a(N_a, N_b)_{\Omega^e} + c(\beta; N_a, N_b)_{\Omega^e}] u_{Db}^e$$

For linear elements

$$C^e = \beta \int_{\Omega^e} \begin{pmatrix} N_1 \frac{\partial N_1}{\partial x} & N_1 \frac{\partial N_2}{\partial x} \\ N_2 \frac{\partial N_1}{\partial x} & N_2 \frac{\partial N_2}{\partial x} \end{pmatrix} dx = \frac{\beta}{2} \begin{pmatrix} -1 & +1 \\ -1 & +1 \end{pmatrix}$$

$$K^e = \nu \int_{\Omega^e} \begin{pmatrix} \frac{\partial N_1}{\partial x} \frac{\partial N_1}{\partial x} & \frac{\partial N_1}{\partial x} \frac{\partial N_2}{\partial x} \\ \frac{\partial N_2}{\partial x} \frac{\partial N_1}{\partial x} & \frac{\partial N_2}{\partial x} \frac{\partial N_2}{\partial x} \end{pmatrix} dx = \frac{\nu}{h} \begin{pmatrix} +1 & -1 \\ -1 & +1 \end{pmatrix}$$

$$f = [f_1^0 \quad f_2^0 \quad \dots \quad f_{(3+...)}^0]_{1 \times 1}$$



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$$(c) \quad Pe = \frac{\beta h}{2\nu} \quad h = \frac{1}{12}$$

$$= \frac{2 \times \frac{1}{12}}{2 \times 0.05} = \frac{1}{6 \times 0.1} = \frac{10}{6} > 1$$

$Pe > 1 \Rightarrow$ It will lead to spurious oscillations
 \therefore The galerkin formulation becomes inaccurate when ~~β~~ convection term dominates diffusion term.

(d) SUPG₂ Stabilisation
Residual

$$R(u) = (\beta \cdot \nabla u - \nabla \cdot (\nu \nabla u)) u$$

For SUPG₂ $P(w) = a \cdot \nabla w$

$$a(w, u) + c(\beta, w, u) + \sum_e \int P(w) \tau R(u) d\Omega = 0$$

$$a(w^h, u^h) + c(\beta, w^h, u^h) + \sum_e \int (\beta \cdot \nabla u^h) \tau [\beta \cdot \nabla u^h - \nabla \cdot (\nu \nabla u^h)] d\Omega = 0$$

Since 1-D conv-diffusion and for linear elements stabilisation term reduces to

$$\boxed{\sum_e \int (\beta \cdot \nabla w^h) \tau (\beta \cdot \nabla u^h)} \quad ; \quad \tau = \nu / \|a\|^2$$

$$\Rightarrow a(w^h, u^h) + c(\beta, w^h, u^h) + \sum_e \int (\beta \cdot \nabla w^h) z(\beta \cdot \nabla u^h) d\Omega = 0$$

$$\sum_{B \in \mathcal{T}_h} \left[\bar{a}(N_a, N_b) + c(\beta, N_a, N_b) \right] u_B + \sum_e \int (\beta \cdot \nabla N_A) z(\beta \cdot \nabla N_B) u_B d\Omega = 0$$

(e) No, the results are not similar to (b) because with ~~the~~ a SUPG stabilization system for $|Pe| > 1$ will be stabilised.

$$\begin{array}{l} \text{Ex-2} \\ \text{(a)} \end{array} \quad \left. \begin{array}{l} -(\nabla \cdot (v \nabla u) - \nabla \cdot p \text{Insd}) = b \quad ; \text{ in } \Omega \\ \nabla \cdot u = 0 \quad \text{in } \Omega \\ u = u_0 \quad \text{on } \Gamma_D \\ (\nabla \nabla u - p \text{Insd}) n = g \quad \text{on } \Gamma_N \end{array} \right\} \begin{array}{l} -2(a) \\ -2(b) \\ -2(c) \\ -2(d) \end{array}$$

~~Introducing~~ Introducing weight functⁿ in 2(a) ~~and~~

$$-\int_{\Omega} w \nabla \cdot (v \nabla u) d\Omega + \int_{\Omega} w (\nabla \cdot p \text{Insd}) d\Omega = \int_{\Omega} w b d\Omega$$

Integrating by parts and by divergence thm.

$$\int_{\Omega} \nabla w : v \nabla u d\Omega - \int_{\Omega} (\nabla \cdot w) p d\Omega = \int_{\Omega} w \cdot b d\Omega + \int_{\Gamma_N} w \cdot g d\Gamma$$

$$a(w, u) - b(w, p) = (w, f) + (w, g)_{\Gamma_N} \quad \forall w \in V \quad] - 2.1$$

similarly introducing weights and integrating ~~parts~~ for eq 2(b) funcⁿ

$$2 = p \in L_2(\Omega) \quad ; \quad q \in Q$$

$$\int_{\Omega} q \nabla \cdot u = 0$$

$$b(u, q) = 0 \quad] - 2.2$$

$$\left[\begin{array}{l} S : \{ v \in H^1(\Omega) \mid u = u_0 \text{ on } \Gamma_D \} \text{ (trial solⁿ)} \\ V : H^1_{\Gamma_D}(\Omega) = \{ w \in H^1(\Omega) \mid w = 0 \text{ on } \Gamma_D \} \text{ (weighting} \\ \text{functⁿ)} \end{array} \right.$$

Eq. 2.1 and 2.2 are the weak forms

(b) Since, P^2 ~~pol~~ functⁿ for velocity and pressure.
 $\Rightarrow Q_2 Q_2$ element, which is unstable because it doesn't satisfy LBB condition

(c) P^2 polynomial functⁿ of vel., pressure, grad. velocity degree, $k = 2$

\Rightarrow Optimal order of convergence for velocity = $k+1 = 3$
grad of velocity = $k+1 = 3$

\therefore convergence will be much faster than that of 1st order.

Numerical solution will be stable

(d) First we will discretize weak form of Stokes problem obtained in 2(a), this
we will write discretize form using G.L.S.

vel comp. are approximated as

$$\left. \begin{aligned} u_i^h(x) &= \sum_{B \in \mathcal{T}_h} N_B(x) u_{iB} \\ u_{D_i}^h(x) &= \sum_{B \in \mathcal{T}_h} N_B(x) u_{D_i}(x_B) \end{aligned} \right\} u_{iB}^h = v_i^h + u_{D_i}^h$$

But vector version of above eq is

$$v^h(x) = \sum w_i^h(x) e_i = \sum_{i=1}^{n_{sd}} \sum_{B \in \mathcal{T}_h} N_B(x) v_{iB} e_i$$

$$w^h(x) = \sum_{i=1}^{n_{sd}} w_i^h(x) e_i$$

~~$p^h(x) = \sum \hat{N}_A(x) p_A$~~

$$p(x) \approx p^h(x) = \sum \hat{N}_A(x) p_A$$

Discretised form of eq 2.1

$$\sum_{j=1}^{nsd} \left\{ \sum_{B \in \eta_{Dj}} a(N_{Ae_i} \cdot N_{Be_j}) u_{jB} \right\} + \sum b(N_{Ae_i}, \hat{N}_A) p_A$$

$$= (N_{Ae_i}, b^h) + (N_{Ae_i}, q^h) \Gamma_N - \sum_{j=1}^{nsd} \left\{ \sum_{B \in \eta_{Dj}} a(N_{Ae_i} \cdot N_{Be_j}) u_{Dj} \right\}$$

Discretized form of eq 2.2

$$\sum_{i=1}^{nsd} \left\{ \sum_{B \in \eta_{Di}} b(N_{Be_i}, \hat{N}_A) u_{iB} \right\} = - \sum_{i=1}^{nsd} \left\{ \sum_{B \in \eta_{Di}} b(N_{Be_i}, \hat{N}_A) v_{Di} \right\}$$

$$\Rightarrow \begin{pmatrix} K & G \\ G^T & 0 \end{pmatrix} \begin{pmatrix} u \\ p \end{pmatrix} = \begin{pmatrix} f \\ h \end{pmatrix}$$

$$K \Rightarrow \int (\nabla N_A)^T (\nabla N_B) d\Omega$$

$N_A \rightarrow$ for weight function w

$$G \Rightarrow \int (\nabla N_A) \hat{N}_A d\Omega$$

\rightarrow discrete gradient operator

$N_B \rightarrow$ for velocity

$$G^T \Rightarrow - \int (\nabla N_B) \hat{N}_A d\Omega$$

\rightarrow Discrete divergence operator

$$f \rightarrow (w, b) + (w, q) \Gamma_N - a(w, v_D)$$

$$h \rightarrow -b(u_D, q)$$

$$e_1 = (1 \ 0 \ 0)^T \quad e_2 = (0 \ 1 \ 0)^T$$

$$e_3 = (0 \ 0 \ 1)^T$$

Introducing G₁LS

$$L(v, p) = \begin{bmatrix} L_1(v, p) \\ L_2(v, p) \end{bmatrix} = \begin{bmatrix} -\nu \nabla^2 v + \nabla p - b \\ \nabla v \end{bmatrix}$$

$$F = \begin{bmatrix} F_1 \\ F_2 \end{bmatrix} = \begin{bmatrix} b \\ h \end{bmatrix}$$

$$L(v, p) = (-\nu \nabla^2 v + \nabla p - b, -\nu \nabla^2 v + \nabla p - b)$$

for w, q (weight functⁿ) ~~for w, q (weight functⁿ)~~

$$(-\nu \nabla^2 w + \nabla q, -\nu \nabla^2 v + \nabla p - b) = 0 \quad \forall (w, q) \in V \times \Omega$$

stabilisation term $\alpha u -$

$$\Rightarrow \begin{cases} (-\nu \nabla^2 w, -\nu \nabla^2 v + \nabla p - b) = 0 & \forall w \in V \\ (\nabla q, -\nu \nabla^2 v + \nabla p - b) = 0 & \forall q \in \Omega \end{cases}$$

Adding these stabilisation terms to galerkin weak form

$$v^h \in S^h \quad p^h \in \Omega^h \quad \forall (w^h, q^h) \in V^h \times \Omega^h$$

$$\begin{cases} a(w^h, v^h) + b(w^h, p^h) + \sum_{\tau \in \mathcal{T}_h} \tau_{\epsilon} (-\nu \nabla^2 w^h, -\nu \nabla^2 v^h + \nabla p^h - b^h) \\ = (w^h, b^h) + (w^h, q^h) \Gamma_N \\ b(v^h, q^h) - \sum_{\tau \in \mathcal{T}_h} \tau_{\epsilon} (\nabla q^h, -\nu \nabla^2 v^h + \nabla p^h - b^h)_{\Omega^e} = 0 \end{cases}$$

$(\nabla q^h, \nabla p^h)$ introduces a non-zero diagonal term in partitioned matrix

Due to G₁LS, equal^{order} interpolations in galerkin formulation becomes stable.

$$\sum_{B \in \Gamma} a (N_A, N_B)_{4B} + \sum_{B \in \Gamma} b (N_{Ae_i}, \hat{N}_A)_{PA} + \sum \tau_e (-\nu \nabla^2 N_A, -\nu \nabla^2 N_A + \nabla N_{\hat{A}} - b)$$

$$\begin{pmatrix} K + \bar{K} & G + \bar{G} \\ G^T + \bar{G} & 0 + \bar{L} \end{pmatrix} = \begin{pmatrix} \bar{f} + \bar{f} & \\ \bar{h} + \bar{f}_q & \end{pmatrix}$$

~~Q~~ ~~Q~~ ~~Q~~

$$\bar{G}^T \rightarrow \sum \int \tau_i (\nabla q_i) (-\nu \nabla^2 v) d\Omega$$

$$\bar{L} \rightarrow \sum \int \tau (\nabla q) \cdot (\nabla p) d\Omega$$

$$\bar{f}_w \rightarrow \sum \int \tau (-\nu \nabla^2 w) \cdot (-f) d\Omega$$

$$\bar{f}_q \rightarrow \sum \int \tau (\nabla q) (-f) d\Omega$$

$$\tau_i = \alpha \frac{h^2}{4\nu}$$

(e) Since it's stable ~~we don't need OLS~~
due to LBB condition

(f)

(e) It is stable ^{due to LBB}, we will ^{still} be requiring
OLS stabilisation

OLS ensures stability

(f) This is stable as LBB condition is
satisfied.